Beginning Code: Imports Write your import commands here:	
What order do you plan to touch the tennis balls?	
What directions will you go in order to reach the first tennis ball?	What code will you use on the motors to make the CodeBot move those directions?
What directions will you go in order to reach the second tennis ball?	What code will you use on the motors to make the CodeBot move those directions?
What directions will you go in order to reach the third tennis ball?	What code will you use on the motors to make the CodeBot move those directions?
What directions will you go in order to reach the fourth tennis ball?	What code will you use on the motors to make the CodeBot move those directions?
What other code do you think you might need in order to meet the 30 second requirement and Why?	